



OR DETERMINISTIC QUALIFYING EXAMINATION

Information:

- Student's full name: _____.
- Student's signature: _____.
- Date: August 15, 2016. Time: 9:00 AM - 1:00 PM.
- Honor pledge: I have neither given nor received unauthorized assistance on this exam.

General instructions: Please carefully read the following instructions:

- Write your name on this sheet. Date and sign on the first page.
- This examination is closed-book, and consists of three questions.
- Answer all three as clearly and concisely as you are able.
- Use of the internet and/or mobile devices is not permitted.

The exam questions

Question 1 (20 points): We have a directed graph G with $n = 50$ nodes, and $n(n - 1) = 2450$ arcs, and arc costs denoted by c_{ij} . We have a distinguished source node s . The goal is to find the shortest path from s to all other nodes.

We first run the label correcting algorithm (LCA), and it finds that there is a negative cost directed cycle in the graph. With the computing resources that we have, we can do ALL of the following, but each of them only once: ?

- We can run the LCA on any graph with a million nodes, which can be assumed to be fully dense (i.e. every possible arc is in the graph), to check whether the graph has a negative cost directed cycle. If it does not, we can run the LCA to find shortest paths from a distinguished node.
- We can solve 1000 linear programming problems with at most 10,000 variables, and 15 thousand constraints each.
- We can run Dijkstra's algorithm on any graph with 10 million nodes, which can be assumed to be fully dense, as long as the graph has only nonnegative arc lengths.
- We can run the label setting algorithm on any graph with 10 million nodes, which can be assumed to be fully dense, as long as the graph is acyclic.
- We can run any algorithm that takes 10^{16} steps, such as comparison, addition, etc.
- We can solve 100 integer programming problems with at most 5000 variables, and 10 thousand constraints each.
- We can find a maximum flow in any graph with 10 million nodes, which can be assumed to be fully dense.

Explain how you would find the shortest paths in G from s to all other nodes.

If you want to do it using, say, option 1, then the total number of steps to construct the bigger graph with at most a million nodes, should be at most 10^{16} .

Question 2 (30 points): We consider the following convex optimization problem:

$$\begin{cases} \min_{x \in \mathbb{R}^n} & c^T x \\ \text{s.t.} & \sup_{a \in \mathcal{P}} a^T x \leq b. \end{cases} \quad (1)$$

where $\mathcal{P} := \{a \in \mathbb{R}^n : Ca \leq d\}$ is a given polyhedron such that $C \in \mathbb{R}^{m \times n}$ and $d \in \mathbb{R}^m$, and $c \in \mathbb{R}^n$ and $b \in \mathbb{R}$ are given. Here, we assume that \mathcal{P} is nonempty.

- Clearly show that this optimization problem can be reformulated equivalently to a linear program (LP). Find its explicit formulation.
- Clearly derive the dual problem of this LP.
- Find the condition on the data C , c and d such that (1) is bounded.

Let us modify problem (1) as follows

$$\begin{cases} \min_{x \in \mathbb{R}^n} & \max_{c \in \mathcal{P}} c^T x \\ \text{s.t.} & Ax = b, \|x\|_\infty \leq \beta. \end{cases} \quad (2)$$

where $\beta > 0$, $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$ are given, and \mathcal{P} is a nonempty, closed, convex and bounded set in \mathbb{R}^n .

- If $\mathcal{P} := \{c : \|c\|_\infty \leq 1\}$, where $\|c\|_\infty = \max_{i=1, \dots, n} |c_i|$, then show that (2) can be written equivalently to an LP. Find the explicit formulation of this LP.
- What is the relation between (2) and the following problem:

$$\begin{cases} \min_{x \in \mathbb{R}^n} & \|x\|_1 \\ \text{s.t.} & Ax = b, \|x\|_\infty \leq \beta, \end{cases} \quad (3)$$

given that \mathcal{P} is given as in Question (d), where $\|x\|_1 := \sum_{i=1}^n |x_i|$? Explain your answer clearly.

Question 3 (30 points): Let $a \in \mathbb{R}^n \setminus \{0\}$, $\beta \in \mathbb{R}$, and consider the hyperplane $H = \{x \in \mathbb{R}^n \mid a^T x = \beta\}$. For any $x_0 \in \mathbb{R}^n$, let

- $d(x_0, H)$ be the Euclidean distance from x_0 to H , and
- $h(x_0)$ be the point in H which is closest to x_0 .

- Prove that $h(x_0)$ is unique.
- Give explicit formulas (in terms of a , β and x_0) for $d(x_0, H)$ and $h(x_0)$.

Let $A \in \mathbb{R}^{m \times n}$ and $b \in \mathbb{R}^m$ be given, and let $P = \{x \in \mathbb{R}^n \mid Ax \leq b\}$. Assume that P has a nonempty interior, i.e. that there is an x satisfying $Ax < b$. Let

- S be the largest sphere in \mathbb{R}^n that is inscribed in P ,
- c be the center of S ,
- r be the radius of S .

- (c) State a linear program which can be used to find S , c and r . Explain carefully how to use your LP to find these quantities. Can your LP also determine whether or not P has a nonempty interior? Explain.

————— **The end** —————